

Engineering as a Force for the Public Good



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UC San Diego: World-Class University

Engineering as a Force for the Public Good



- **We Are:**
 - Student-centered
 - Research-focused
 - Service-oriented
 - Public university

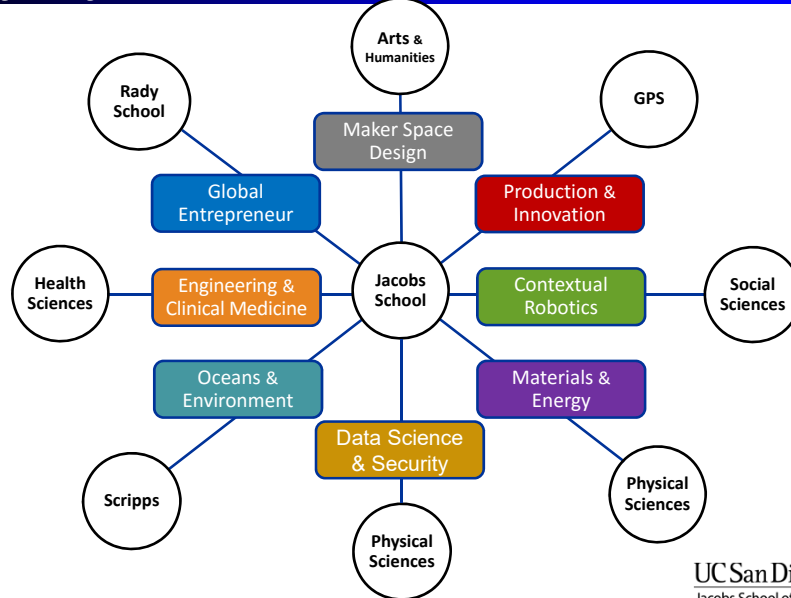
- **One of the top 15 research universities worldwide.**
- **#7 Among Engineering Schools in the U.S.**
 - U.S. News ranking of Best Global Universities, 2014
- **Largest Engineering School in California**

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Initiatives with Campus Partners

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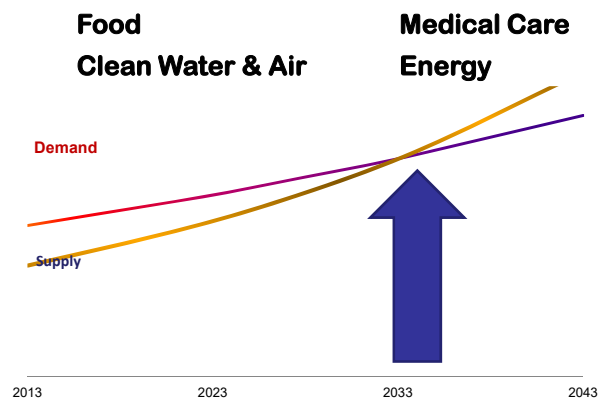
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Introduction to Abundance*

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- Abundance* movement forecasts an elimination in one generation (20 to 30 years) of major global problems:



4

* <http://www.abundancethebook.com/>

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Abundance* Enablers

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Exponential Technologies that Promise to Grow Into Large Markets Quickly

- Biotechnology and bioinformatics
- Medicine
- Nanomaterials and nanotechnology
- Networks and sensors
(45 trillion networked sensors in 20 years)
- Digital manufacturing (3D printing) and infinite computing
- Computational systems
- Artificial intelligence
- Robotics

5

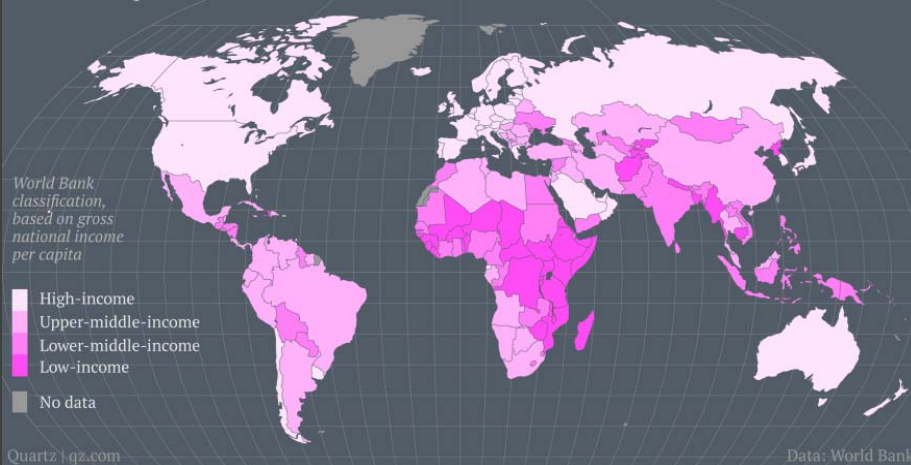
* <http://www.abundancethebook.com/>

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Bill Gates: No Poor Countries by 2035

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The world's poorest countries



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<http://qz.com/168341/bill-gates-predicts-there-will-be-almost-no-poor-countries-by-2035/>

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Engineering for the Public Good

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Medical Advances



Sustainable Energy Technologies



Transportation Safety



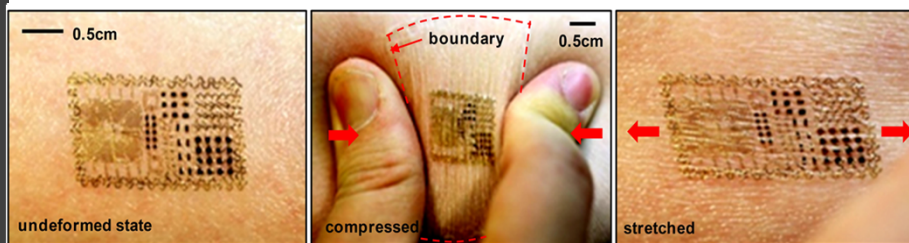
Solutions for Developing World

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Elastic Epidermal Electronics

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Professor Todd P. Coleman, Bioengineering

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Science, Aug 12, 2011

UCSD Center for Perinatal Health

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Unobstructive Monitoring

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Lifespan Home Care Technologies

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Center for Mobile Health Systems and Applications

Prototype, develop and evaluate technologies that support home care across the lifespan in a user-centered way

- Reduce hospital re-admissions
- Promote successful aging
- Smart-home technologies that anticipate health problems
- Supporting care-givers of patients with chronic, debilitating disease
- Reducing costs of medical care



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HEALTH SCIENCES

The Design Lab
Think. Observe. Make.



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Wireless Sensing and Diagnostics

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Center for Mobile Health Systems and Applications

- Sensing and measurement of air, water, soil and food quality
- Track infectious diseases and sequelae
- Inexpensive diagnostics using mobile phones
- Technologies for healthcare in remote settings
- Data-driven approaches to disease surveillance and population health



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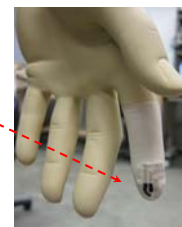
Whole Body Wearable Sensors

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Fitness Textile Sensor



Metabolite Sensor with Electronics



Forensic Finger Sensor

Any-place, all-day, non-invasive monitoring directly on the skin or textile
Reducing health-care costs and enhancing the quality of life

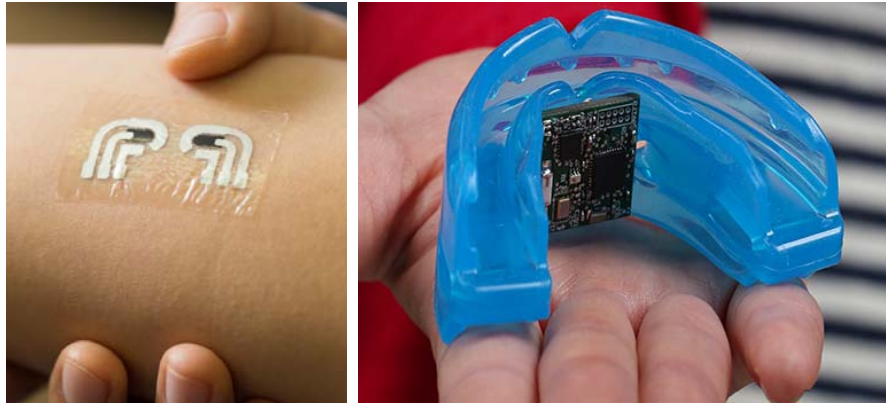
Head to toe

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Non-Invasive Monitoring

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Non-Invasive Monitoring of Glucose and Saliva Biomarkers

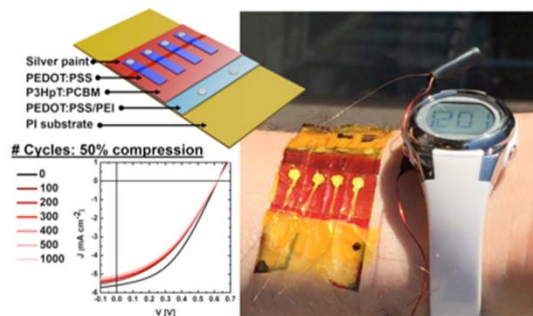
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Flexible Electronics

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A future in which organic electronics and biological tissue can interact seamlessly



Flexible organic solar cells

- Molecularly stretchable electronics
- Whole devices that can degrade under physiological conditions
- Conjugated polymers capable of self-healing

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Professor Darren Lipomi, NanoEngineering

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Harvesting Energy from Skin

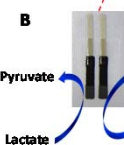
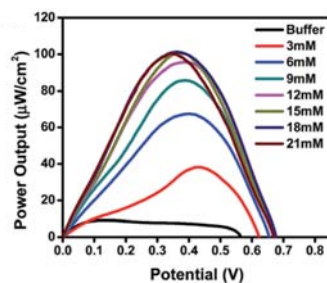
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Watch "OFF"



Watch "ON"



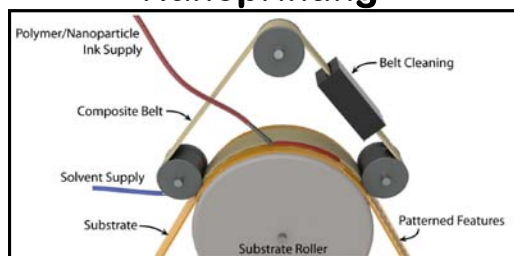
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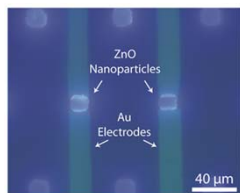
Printable Nanoelectronics

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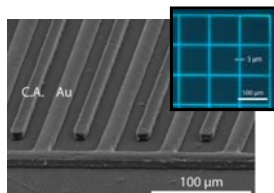
Nanoprinting



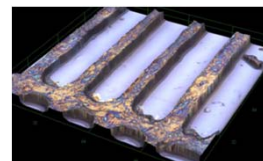
Several Applications



UV Sensors



Biosensors



Organic Electronics

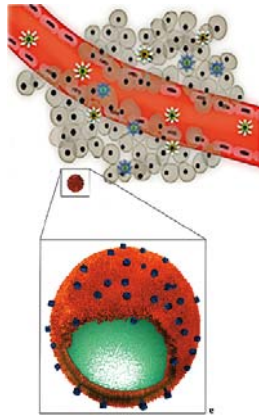
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E. Erdem, et al., Small, 2013. M. Demko, et al., ACS Nano, 2012

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Precision Delivery of Drugs

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Targeted Combinatorial Drug Delivery for Cancer Therapy and Beyond

Loading of multiple drugs in desired proportions onto a nanocarrier. Next, nanocarrier is delivered to the cell of interest.

Antimicrobial Drug Delivery

Delivery of antimicrobial drugs to kill bacteria, fungi and viruses that can't otherwise be safely and effectively delivered

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Professor Liangfang Zhang, Nanoengineering

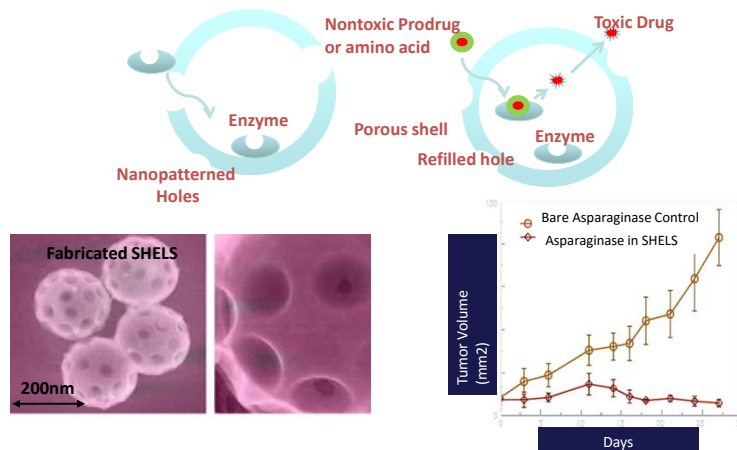
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Manufacturing Drugs in the Body

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Syn Hollow Enzyme-Loaded nanoShell

Inanc Ortac and Sadik Esener (NanoEngineering & MCC)



Nano Letters
January 2014

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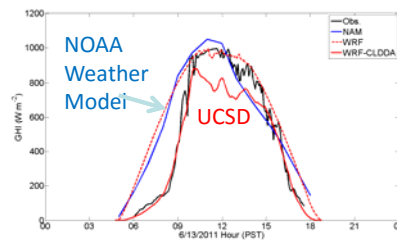
In Vivo Proof of concept: Pancreatic tumor cannot grow when IM injected, asparaginase loaded SHELS distant from tumor depletes serum asparagine

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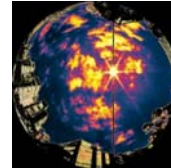
Sustainable Energy Technologies

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Professor Jan Kleissl, Mechanical & Aerospace Engineering



Solar forecasting research
enables the power grid to
accommodate more solar power.



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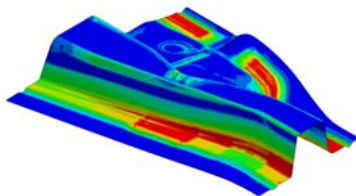
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Computational Mechanics

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Single Surface Contact Algorithm for Crash Simulation

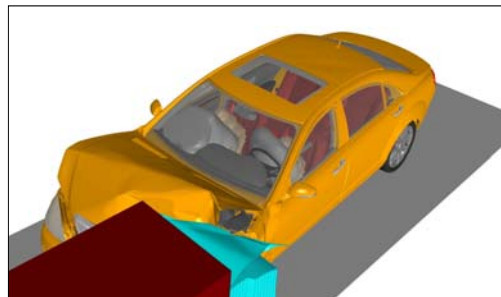
Professor David Benson, Structural Engineering



Component
manufacturing
simulation

Final product performance

This research is used in all
commercial codes to design
cars to meet government
crashworthiness standards
worldwide.



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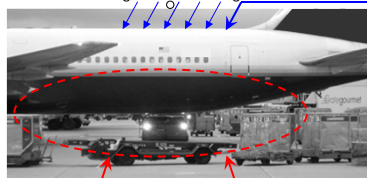
Composite Structures Aviation Safety

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Professor Hyonny Kim, Structural Engineering

Investigation focused on non-visible damage formation in modern carbon-fiber composite aircraft structures.

Challenge: **blunt impact threats** creating internal damage **showing little or no exterior visibility**



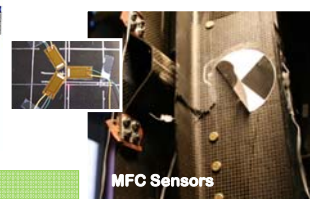
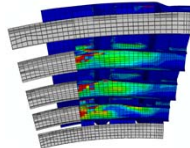
Hail Ice Impact



Ground Vehicles & Equipment Contact



UCSD Lab Test



MFC Sensors

Research Outcomes:
→ **improved safety**

- new model-prediction capabilities
- damage modes observation and awareness
- damage detection via robust sensor system

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Advanced, Multifunctional Materials

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Multifunctional Materials
Research Lab (MMRL)



To the Moon and the Mars:

"Lunar cement" and "Martian cement" Based on Lunar/Martian Soils

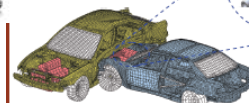
Advanced, Multifunctional
Structural Materials

From the Earth:

- Protective Materials for Military and Sports, e.g. Next-Generation Humvee Floor & Mat to mitigate roadside bombs
- Next-generation electric vehicles (EV) using today's or near-future batteries – robust & multifunctional battery systems



Commercializing Electric
Vehicles with Today's or
Near-Future Batteries



Professor Yu Qiao, Structural Engineering

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CitiSense: Air Quality via the Crowd

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Mobile personal sensing for regional air quality monitoring

Machine learning predicts future conditions

Two month-long user deployments in San Diego region

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Griswold, Dasgupta, Krueger, Rosing (CSE), Patrick (SOM)

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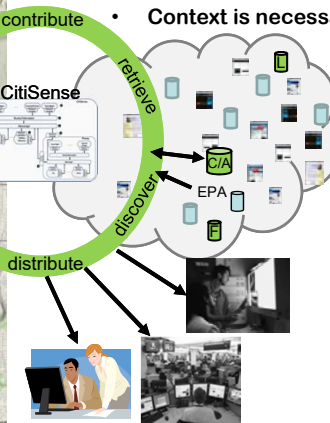
CitiSense

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Changing user behavior with intelligent sensor feedback



- CitiSense sensors given to commuters
- Participants using the sensors found “urban valleys” where buildings trapped pollution
- Sensor feedback changed user behavior
- Context is necessary to achieve results



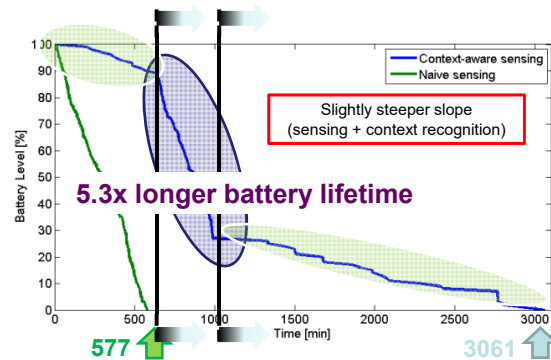
UCSD's NSF CitiSense Project

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Context-awareness in Urban Sensing

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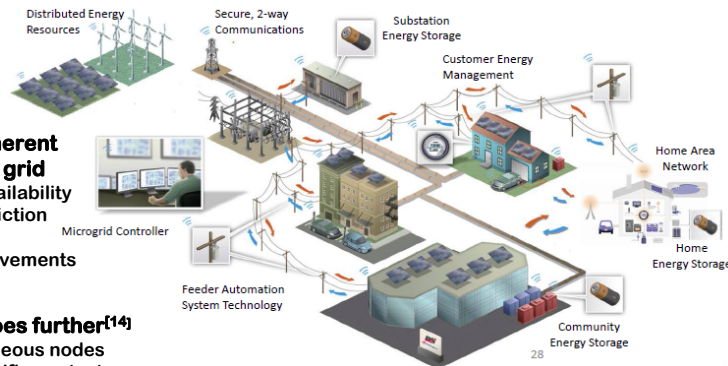
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Context-awareness in Smart Grid

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- **Context is inherent in the energy grid**
 - Source availability
 - Load prediction
 - Pricing
 - People movements
- **Smart grid goes further^[14]**
 - Heterogeneous nodes
 - Node-specific context:
 - e.g. energy use, load flexibility, energy limits
 - Improved prediction
 - Improved stability – better matching of loads and sources limits frequency deviation
- **Our initial focus is on context-aware residential energy management**



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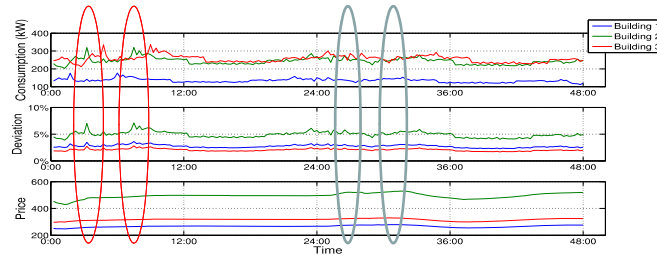
[14] National Institute of Standards and Technology. www.nist.gov

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Distributed Control

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Swarm of Buildings Connected to a Smart Grid



- Swarm of smart buildings connected to the grid
- Each building has its own controller -> distributed control
- Smart grid reacts with pricing and stability signals
- Enables a study of system stability

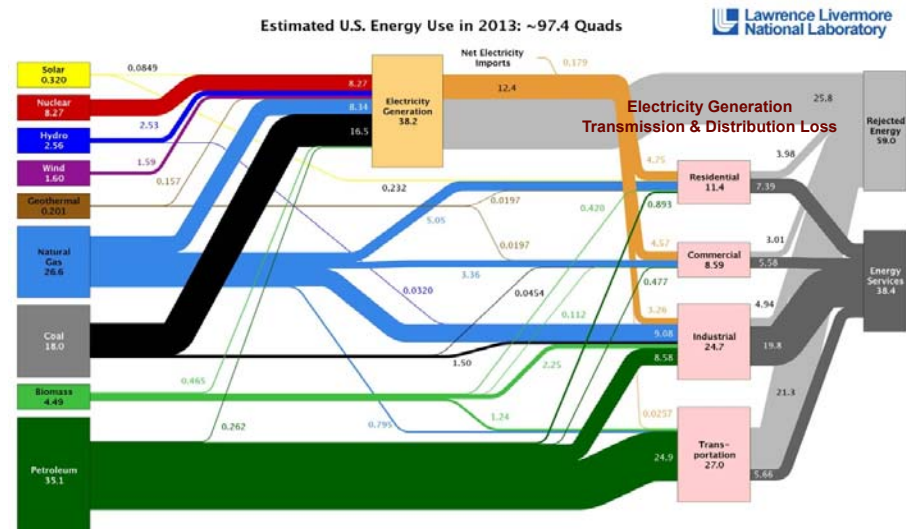
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B. Aksanli, A.S. Akyurek, M. Behl, M. Clark, A. Donze, P. Dutta, Patrick Lazik, M. Maasoury, R. Mangharam, T.X. Nghiem, V.Raman, A. Rowe, A. Sangiovanni-Vincentelli, S. A. Seshia, T. S. Rosing, J. Venkatesh. **Distributed Control of a Swarm of Buildings Connected to a Smart Grid**, 1st ACM International Conference on Embedded Systems For Energy-Efficient Buildings (BuildSys), 2014

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Energy Landscape of the USA in 2008

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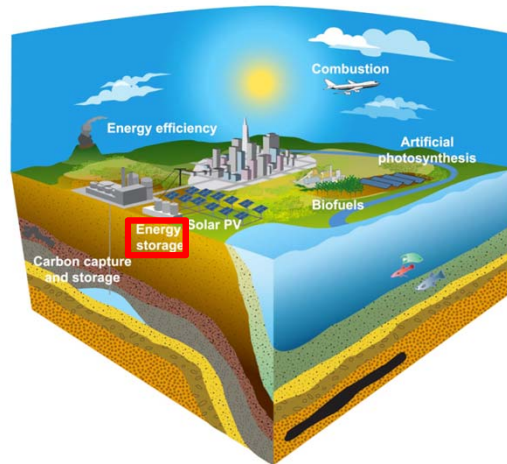


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Distributed Generation & Storage

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Energy For a Sustainable Future



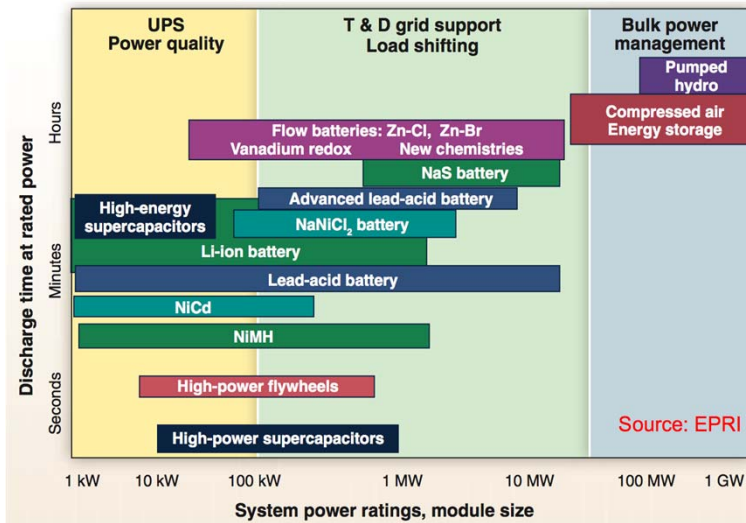
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Courtesy of Lawrence Berkeley National Lab

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Distributed Generation & Storage

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Courtesy of Lawrence Berkeley National Lab

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A Living Laboratory for Sustainability

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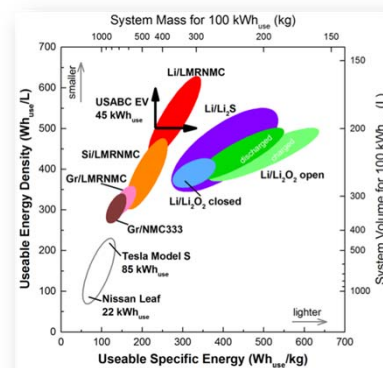
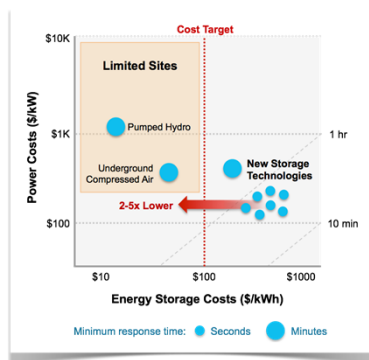
**45MW Microgrid -- 6MW Solar Penetration
3MWh ESS**

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Innovation Needed in Energy Storage

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Dr. Ping Liu ARPA/e

Courtesy of Argonne National Lab

Goals to Reach in the Next Decade:

Increase Energy Density 2X
Lower the Cost Wh/Kg 2X

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Why We Need Better Batteries

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Low power
Safety



High power
(\$/kW)
High energy
(Wh/kg & /L)



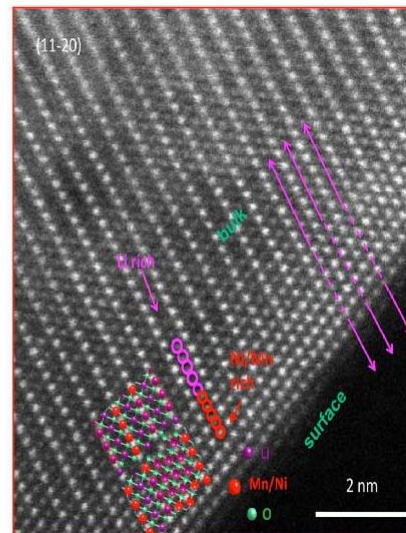
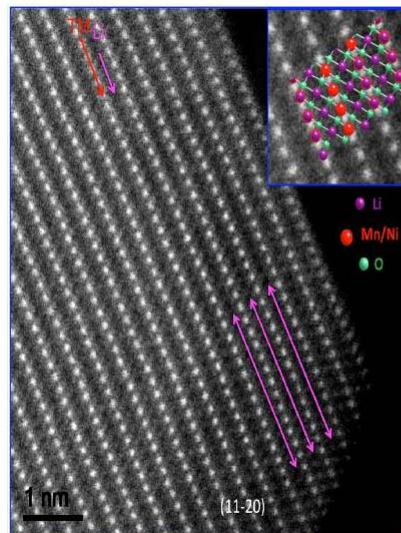
System cost
(\$/kWh)
Reliability

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Imaging Atoms in a Working Battery!

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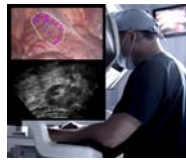


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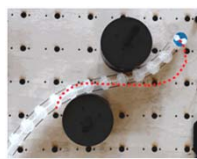
Advanced Robotics and Controls

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Medical Robotics

- Algorithms for robot-assisted control of instruments
- Augmented Reality to “see under the tissue”
- Design of smart, robotic instruments for new applications



Dexterous, Flexible Robotics

- Design and control of soft, flexible robots
- biomimetic locomotion and manipulation
- Flexible robotic applications in medicine, automotive/aerospace, military



Robotic Actuators and Biomimetic Design

- Novel actuators and biomimetic mechanisms
- Applications for robotic limbs, prostheses and orthoses
- Provide insight into how nature controls similar biology

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Michael Yip, Electrical and Computer Engineering

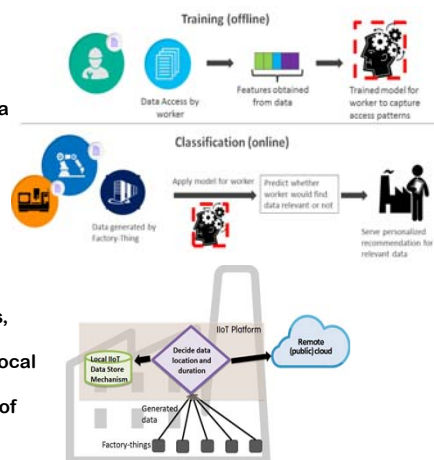
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Smart Factories

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Recommendation System for Smart Factory IIoT Data Access and Cloud Storage

- Information overload in smart factories
 - Workers access data for monitoring and reporting
 - Overwhelmed by size and diversity of data
- Data Access Recommendation System
 - Connect factory workers with relevant IIoT data
- Hierarchical Cloud Storage
 - Achieve trade-off between time to access, bandwidth used, and storage cost
 - Advanced analytics identify and store in local cloud frequently used and sensitive data
 - Sampling techniques determine duration of data storage based on predicted usage



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Center for Wireless Communications

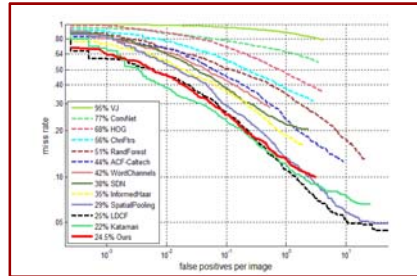
Sujit Dey, Truong Nguyen; in collaboration with KETI

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Real-time Object Recognition

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- Goal:
 - **efficient classifiers** that optimize trade-off between object detection accuracy and speed
 - **real time classification of 1,000,000 image windows per second**
- Methods:
 - cascades of deep learning classifiers learned with boosting
- Applications:
 - **robotics, smart vehicles, state of the art pedestrian detection**



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SVCL UCSD

Nuno Vasconcelos, Electrical and Computer Engineering

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Robotic Teams

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Human-swarm interaction and resource allocation in robotic teams

Goal: enable human to easily specify swarm behaviors for:

- Creating a safety perimeter
- Searching an urban environment
- Rerouting traffic
- Achieving area coverage
- Creating egress path for victims
- Providing situational awareness



Turtlebots



Parrot quadrotors



Android app

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Jorge Cortez, Sonia Martinez, Multi-Agent Robotics Laboratory

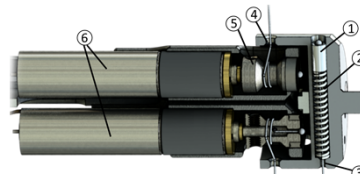
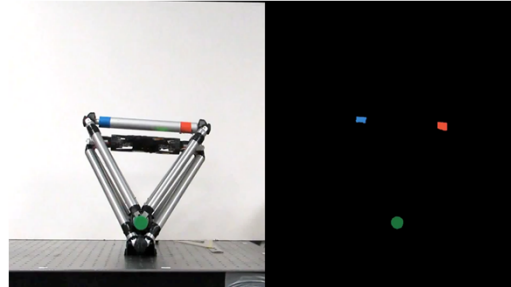
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Tensegrity Duct-Climbing Robot

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design by
Jeff Friesen



Two nested tetrahedra interconnected by actuable tendons. Chimneys up ducts like a rock climber. Maneuverable, strong, and mass/volume efficient. Precision construction.



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Thomas Bewley, Mechanical and Aerospace Engineering

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IceCube

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design by
Andrew
Cavender



IceCube (top, patent pending) accelerates by gimballing CMGs (heavy flywheels) which store rotational inertia. Zippy!

Competing GuardBot design (right) accelerates by moving a mass to the size of sphere, causing it to roll. Not so zippy.



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Thomas Bewley, Mechanical and Aerospace Engineering

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Sensor Balloons in Hurricanes

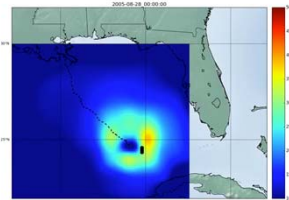
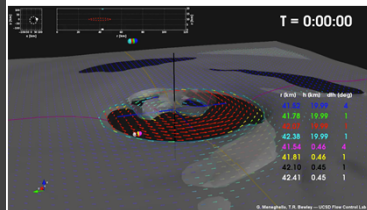
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control
design by
Gianluca
Meneghello

Underactuated control of sensor balloon distribution in hurricanes

Leverage predictable stratification of hurricane flowfield (inflow towards core at low altitudes, outflow at high altitudes) to regulate balloon distribution.

Persistent in situ measurements of temperature, pressure, humidity, winds, and precipitation over hurricanes. Better and cheaper than dropsondes!



Altitude cycling balloon
technology developed
by *Thin Red Line*.



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Thomas Bewley, Mechanical and Aerospace Engineering

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Multiagent Coordination

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Multiagent coordination for building exploration

Challenge: alarm goes off at large superstore.
First responder at scene needs situational awareness asap.

collaboration with
Peter Yanofsky et al.
WowWee Robotics
and
Clark Briggs et al.
ATA Engineering

Solution: Send in the 'bots! Several quick/inexpensive toy-grade bots with IR cameras for thermal measurement, electronic noses for fume detection, and cellphone-grade electronics for mapping and communication.



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Thomas Bewley, Mechanical and Aerospace Engineering

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Embedded Control & Robotics Course

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Senior/MS-level. "Capstone".
UCSD + extensive industry involvement.
Turning into a Massively-Open Online Course (MOOC) with hardware.

Inexpensive kits: EduMIP, EduRover
Four Stages:

- * **Build**, and extend the design.
Collaborative mechanical & electrical CAD.
3D printing, custom PCB design/fab.
- * **Model** electrical and mechanical properties.
Kinematics & Dynamics. Linear Circuits.
PWM, H-Bridges, encoders.
- * **Program** in embedded linux and C.
Graphical programming. SPI, I2C, GPS, R/C.
Multithreading. RTOSs. Low-cost ARMs.
- * **Feedback Control Design**. Interconnection of
continuous-time plant and low-pass filters
with discrete-time microcontroller.



Vehicle designs by James Strawson,
commercialized in collaboration with
Peter Yanofsky et al., *WowWee Robotics*.

Thomas Bewley, Mechanical and Aerospace Engineering

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Biologically Inspired Robotic Design

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Autonomous
Soft Systems



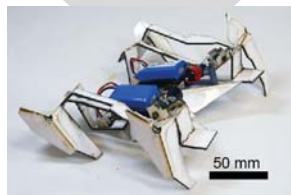
Self-Assembly
by Folding



Functionally
Graded Materials



Soft Robotics, 1:3, pp. 213-223



Science, 345:6197, pp. 644-646



Science, 349:6244, pp. 161-165

Bioinspired Robotics and Design Lab

Michael Tolley, Mechanical and Aerospace Engineering

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